

PH40S TABLE OF INFORMATION

CONSTANTS	
Proton mass, $m_p = 1.67 \times 10^{-27}$ kg	Elementary charge, $e = 1.60 \times 10^{-19}$ C
Neutron mass, $m_n = 1.67 \times 10^{-27}$ kg	Coulomb's law constant, $k = 9.0 \times 10^9$ N·m ² /C ²
Electron mass, $m_e = 9.11 \times 10^{-31}$ kg	Universal gravitational constant, $G = 6.67 \times 10^{-11}$ m ³ /kg · s ²
Mass of Earth, $m_{Earth} = 5.98 \times 10^{24}$ kg	Acceleration due to gravity at Earth's surface, $g = 9.8$ m/s ²
Radius of Earth, $r_{Earth} = 6.38 \times 10^6$ m	Speed of light, $c = 3.00 \times 10^8$ m/s

UNIT SYMBOLS					
meter, m	second, s	joule, J	watt, W	volt, V	
kilogram, kg	newton, N	hertz, Hz	coulomb, C	ohm, Ω	

METRIC PREFIXES		
Factor	Prefix	Symbol
10^{12}	tera	T
10^9	giga	G
10^6	mega	M
10^3	kilo	k
10^{-2}	centi	c
10^{-3}	milli	m
10^{-6}	micro	μ
10^{-9}	nano	n
10^{-12}	pico	p

GEOMETRY	
Rectangle	$A = \text{area}$
$A = bh$	$C = \text{circumference}$
Triangle	$V = \text{volume}$
$A = \frac{1}{2}bh$	$S = \text{surface area}$
Circle	$b = \text{base}$
$A = \pi r^2$	$h = \text{height}$
$C = 2\pi r$	$\ell = \text{length}$
Rectangular solid	$w = \text{width}$
$V = \ell wh$	$r = \text{radius}$
Cylinder	
$V = \pi r^2 \ell$	
$S = 2\pi r\ell + 2\pi r^2$	
Sphere	
$V = \frac{4}{3}\pi r^3$	
$S = 4\pi r^2$	

PH40S EQUATIONS

MECHANICS	ELECTRICITY AND MAGNETISM
$v = v_0 + at$	$a = \text{acceleration}$
$x = \left(\frac{v_0 + v}{2}\right)t$	$A = \text{amplitude}$
$x = v_0 t + \frac{1}{2}at^2$	$d = \text{distance}$
$v^2 = v_0^2 + 2ax$	$E = \text{energy}$
$F_{\text{net}} = \sum F = ma$	$F = \text{force}$
$F_g = mg$	$f = \text{frequency}$
$ F_f = \mu F_N $	$K = \text{kinetic energy}$
$a_c = \frac{v^2}{r}$	$k = \text{spring constant}$
$v = \frac{2\pi r}{T}$	$m = \text{mass}$
$T = \frac{1}{f}$	$P = \text{power}$
$p = mv$	$p = \text{momentum}$
$\Delta p = F\Delta t$	$r = \text{radius or separation}$
$W = Fd \cos \theta$	$T = \text{period}$
$\Delta K = \sum W_i$	$t = \text{time}$
$K = \frac{1}{2}mv^2$	$U = \text{potential energy}$
$U_g = mgh$	$v = \text{speed (velocity)}$
$ F_s = k x $	$W = \text{work done on a system}$
$U_s = \frac{1}{2}kx^2$	$x = \text{position}$
	$\mu = \text{coefficient of friction}$
	$\theta = \text{angle}$
	$P = \frac{W}{t} = \frac{\Delta E}{\Delta t}$
	$F_g = G \frac{m_1 m_2}{r^2}$
	$g = G \frac{m}{r^2}$
	$U_g = -G \frac{m_1 m_2}{r}$
	$F_E = k \frac{q_1 q_2}{r^2}$
	$E = \frac{F_E}{q}$
	$E = k \frac{q}{r^2}$
	$U_E = k \frac{q_1 q_2}{r}$
	$U_E = qE\Delta d$
	$V = k \frac{q}{r}$
	$U_E = qV$
	$E = \frac{\Delta V}{d}$
	$F_M = BIl \sin \theta$
	$F_M = qvB \sin \theta$
	$I = \frac{\Delta Q}{\Delta t}$
	$R = \rho \frac{L}{A}$
	$V = IR$
	$R_s = \sum_i R_i$
	$\frac{1}{R_p} = \sum_i \frac{1}{R_i}$
	$P = IV = I^2R = \frac{V^2}{R}$
	$\frac{I_s}{I_p} = \frac{V_p}{V_s} = \frac{N_p}{N_s}$